

# Robustifying machine-learned algorithms for efficient grid operation

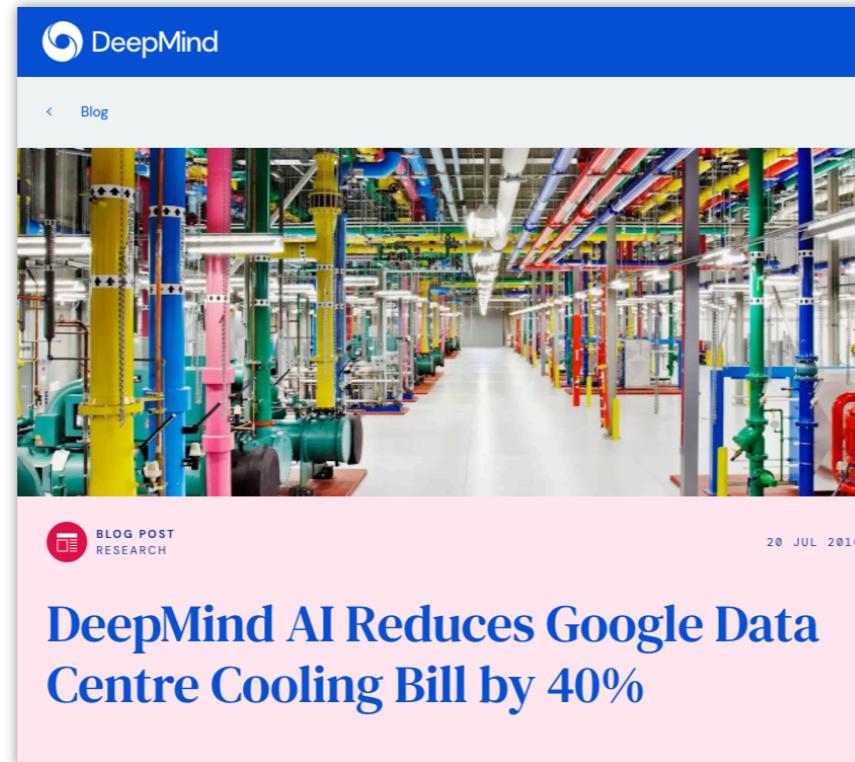
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# AI/ML achieves state-of-the-art performance in many domains:



# But...

**past performance does not guarantee future results!**



**General question:** Can we endow AI/ML algorithms with worst-case performance guarantees?

**Our paper:** “Robustifying” the performance of black-box ML algorithms for generation dispatch

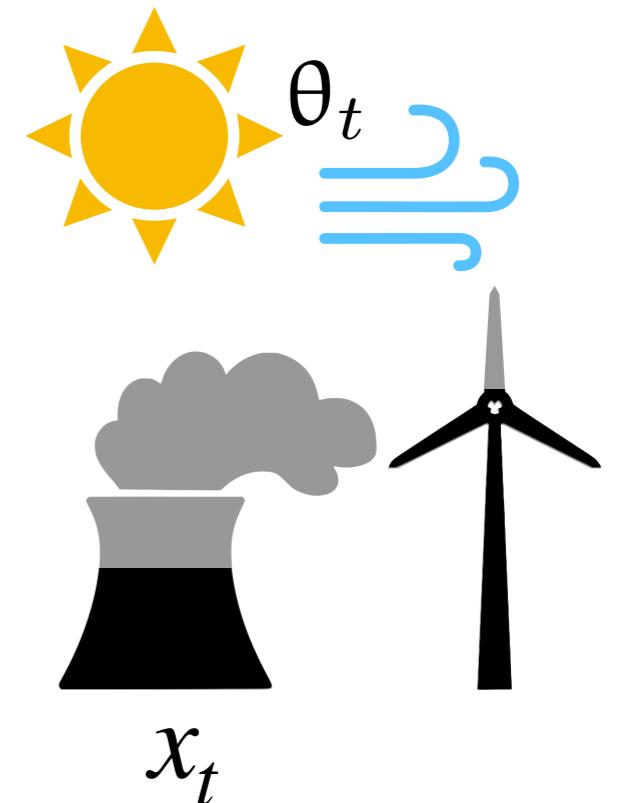


Tesla estimates there are 60,000 of its cars, like this Model Y, using its "Full Self-Driving" beta software on public roads today. (TWP)

# Problem setting: Generation dispatch with ramp costs

Generation operator faces a sequential problem:

1. At time  $t$ , observe ambient conditions  $\theta_t$  (demand, wind, sun, temperature, etc.)
2. Choose dispatch level(s)  $x_t \in X_t$
3. Pay fuel cost  $f(x_t; \theta_t)$  and ramp cost  $\|x_t - x_{t-1}\|$



$$\text{Total cost: } \sum_{t=1}^T f(x_t; \theta_t) + \|x_t - x_{t-1}\|$$

Often (potentially inaccurate) predictions  $\hat{\theta}_{t+1|t}, \dots, \hat{\theta}_{t+w|t}$  of future conditions are available

# Dispatch algorithms in practice

$$\text{GREEDY} : \boldsymbol{\theta}_t \mapsto \arg \min_{\mathbf{x} \in \mathbb{R}^d} f(\mathbf{x}; \boldsymbol{\theta}_t) =: \mathbf{x}_t.$$

(i.e., single-step economic dispatch)

$$\text{MPC} : \boldsymbol{\Theta} \mapsto \arg \min_{\substack{\mathbf{x} \in \mathbb{R}^d \\ \mathbf{y}_1, \dots, \mathbf{y}_w \in \mathbb{R}^d}} f(\mathbf{x}; \boldsymbol{\theta}_t) + \|\mathbf{x} - \mathbf{x}_{t-1}\| + \sum_{\tau=1}^w f(\mathbf{y}_\tau; \hat{\boldsymbol{\theta}}_{t+\tau|t}) + \|\mathbf{y}_\tau - \mathbf{y}_{\tau-1}\| =: \mathbf{x}_t$$

(model predictive control)

But... MPC will be intractable if  $f(\cdot; \theta)$  is nonconvex!

Idea: train an ML algorithm (offline) to mimic MPC

But: ML algorithm generally won't come with worst-case guarantees

Wish to exploit its (likely) good performance while providing worst-case guarantees

# Robustifying black-box ML algorithms

Idea: switch back and forth between ML and Greedy algorithms

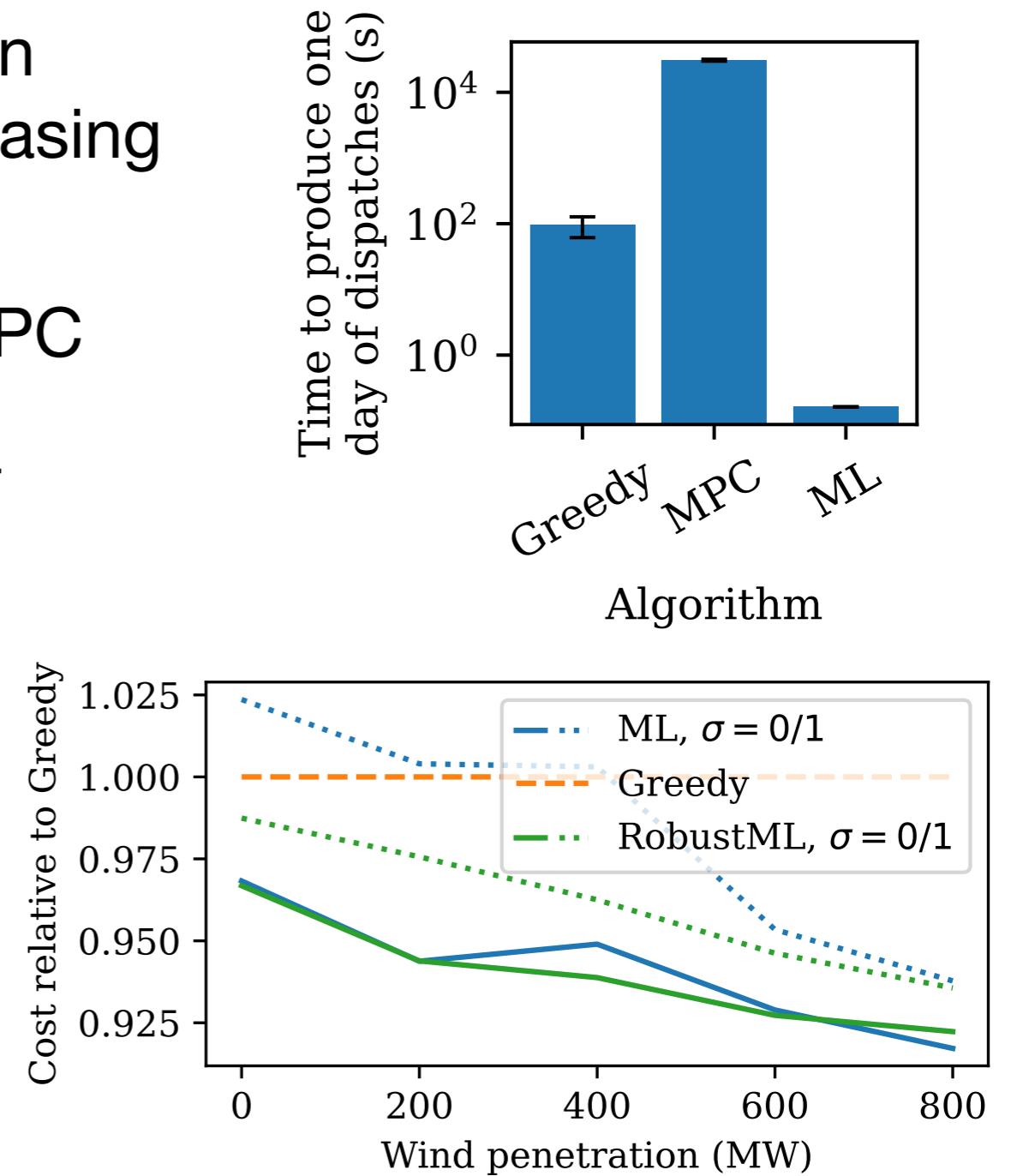
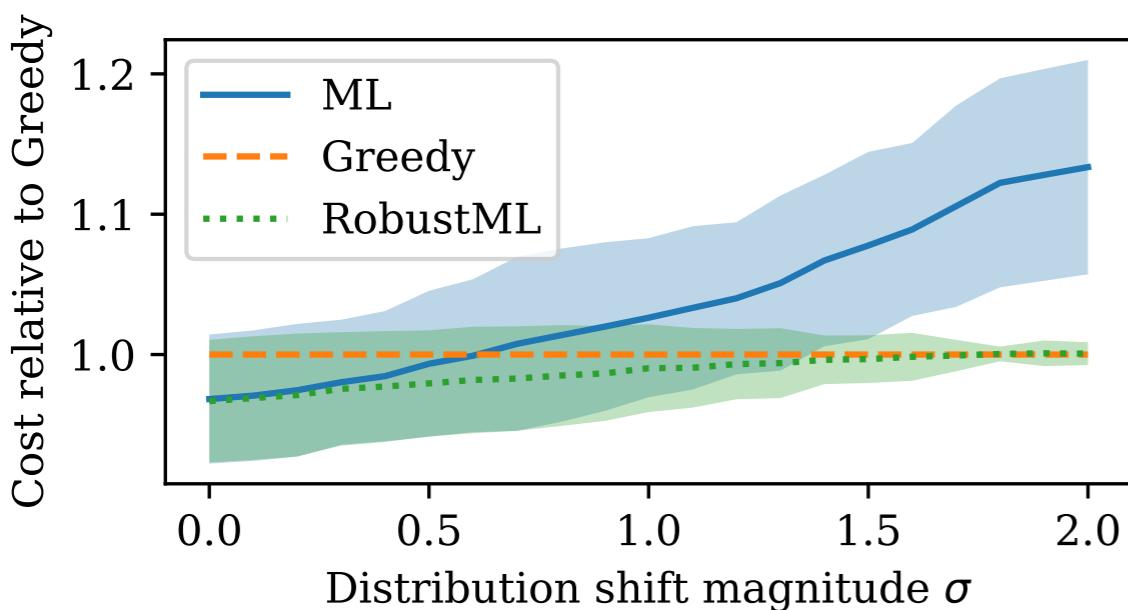
- Follow ML decisions until  $\text{Cost(ML)}$  surpasses some threshold  $h$
- Increase  $h$  and switch to following the Greedy algorithm until  $\text{Cost(Greedy)}$  surpasses  $h$
- Increase  $h$ , switch back to ML and repeat...

**Theorem.** For any  $\epsilon > 0$ , our algorithm **RobustML** achieves cost bounded by

$$\min\{(1 + \epsilon)\text{Cost(ML)}, \mathcal{O}(\epsilon^{-1})\text{Cost(Greedy)} + \mathcal{O}(D\epsilon^{-1})\}$$

# Experiments: Grid Cogeneration

- Codispatch of electricity & steam on two thermal generators under increasing wind penetration
- Train ML to replicate behavior of MPC
- Combine with Greedy algorithm via RobustML



# Thanks for listening!

**Please feel free to reach out at [nchristi@caltech.edu](mailto:nchristi@caltech.edu)**

## Reference:

N. Christianson, C. Yeh, T. Li, M. Torabi Rad, A. Golmohammadi, and A. Wierman.  
*Robustifying machine-learned algorithms for efficient grid operation*. Workshop  
on Tackling Climate Change with Machine Learning at NeurIPS 2022.

