

# Addressing Deep Learning Model Uncertainty in Long-Range Climate Forecasting with Late Fusion

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# Motivation

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- Long range climate forecasting can save lives and property
  - High impact extreme events, e.g., heat waves, cold fronts, floods, droughts can result in tremendous loss of lives and property
  - The longer the range of accurate forecasting, the more the time for preparation and response
- Deep learning models
  - Become more popular on climate forecasting
  - Model uncertainties – models trained with identical hyperparameters are usually different
  - Model uncertainties can be more prominent with limited climate data
  - Reduce reliability especially with long-range forecasting
- Goal
  - Reduce deep learning model uncertainties and improve accuracy in seasonal forecasting

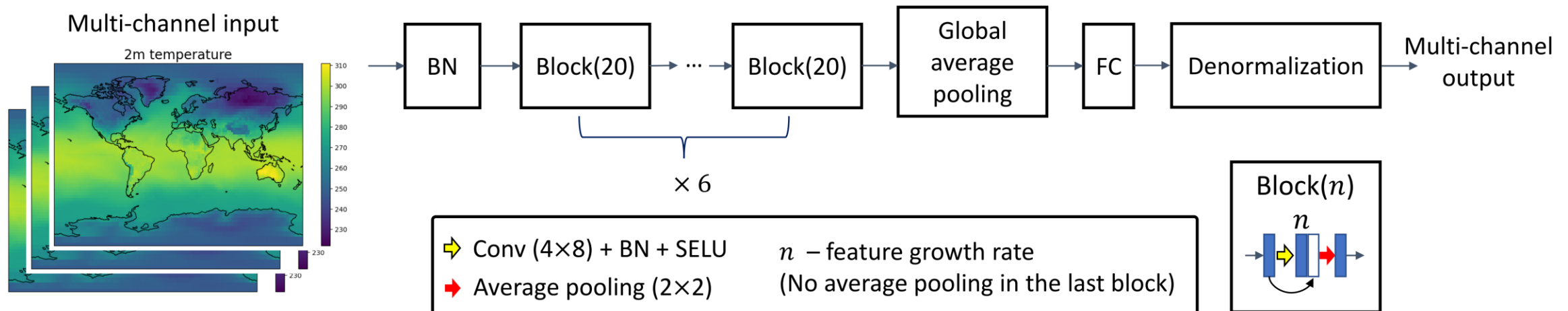
# Contributions

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- Propose a network architecture for 2m temperature prediction
  - Denormalization layer – provides the benefits of data normalization without normalizing the data
- Propose a late fusion approach that systematically combines the predictions from multiple models to reduce expected errors of the fused results

# Network Architecture for 2m Temperature Forecasting

- Convolutional neural network
  - Multi-channel input tensor formed by stacking the maps of 2m temperature of a fixed input horizon
  - Multi-channel output, each channel contains the 2m temperature of a location at a fixed lead time
    - E.g., 8 locations  $\rightarrow$  8 channels (scalars)
  - Six dense blocks, each with one convolutional layer with 20 filters
  - Batch normalization (BN) layer as the first layer for input data normalization
  - Denormalization layer as the last layer:  $x_o(c) = x_i(c)\sigma(c) + m(c)$ 
    - The fully connected (FC) layer only needs to provide normalized prediction  $\rightarrow$  same advantage as normalizing observed data



# Late Fusion

- Late fusion

Combines predictions from different models to **reduce expected errors from all models**:

$$f(s_i) = \sum_j w^j f^j(s_i) \quad \text{with} \quad \sum_j w^j = 1 \quad (1)$$

where  $f^j(s_i)$  is the prediction by the  $j$ th model of input  $s_i$ . The pairwise correlation between models  $j_1$  and  $j_2$  is:

$$M[j_1, j_2] = \sum_i [f^{j_1}(s_i) - t(s_i)] [f^{j_2}(s_i) - t(s_i)] \quad (2)$$

with  $t(s_i)$  the true value. The weights are then computed (from the validation data) by:

$$\mathbf{w} = \arg \min_{\mathbf{w}} \mathbf{w}^T \mathbf{M} \mathbf{w} = \frac{\mathbf{M}^{-1} \mathbf{1}_K}{\mathbf{1}_K^T \mathbf{M}^{-1} \mathbf{1}_K} \quad (3)$$

with  $K$  the number of models to be fused

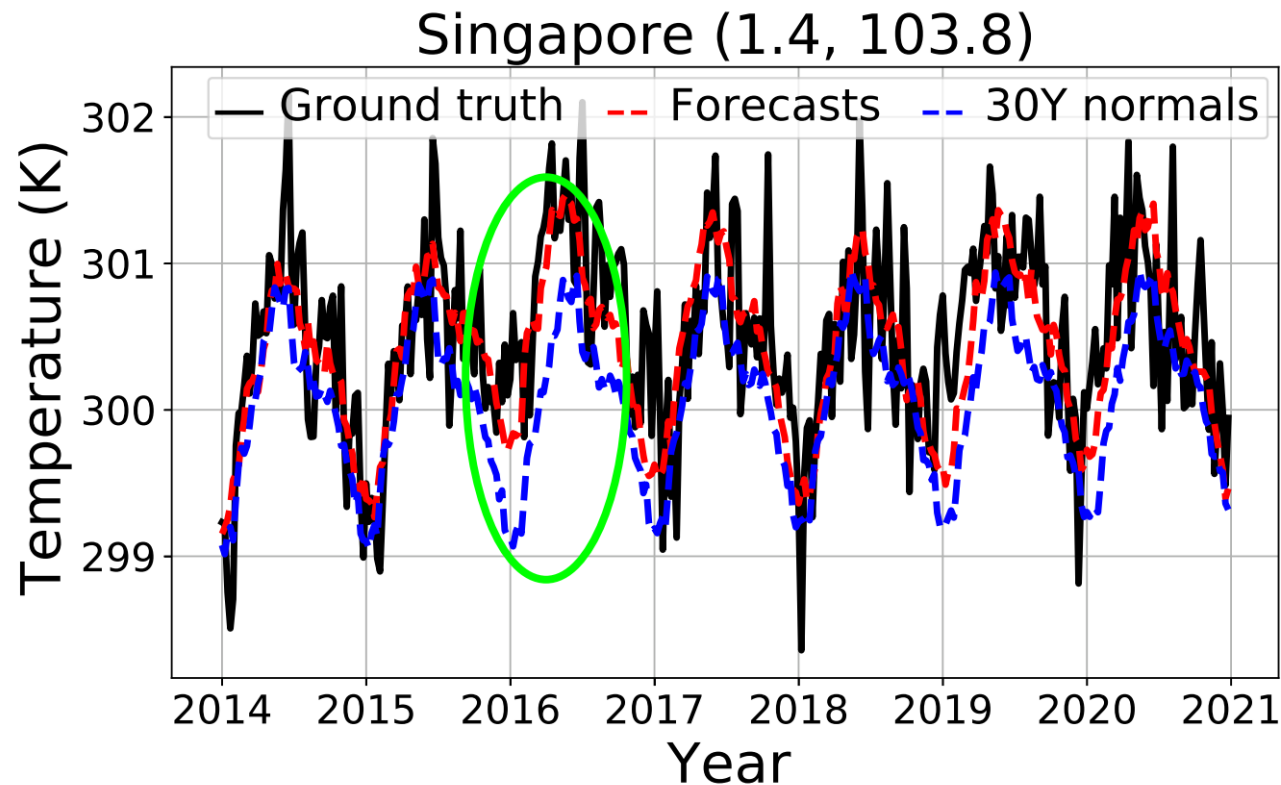
# Experiments

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- Data – 2m temperature maps of the ERA5 reanalysis data
  - Training – 1979 – 2007 (1508 weeks)
  - Validation – 2008 – 2011 (208 weeks)
  - Testing – 2012 – 2020 (468 weeks)
- Frameworks
  - Trained 20 models per lead time
  - **Late fusion** – at each lead time, predictions of all models were combined
  - **Best model** – at each lead time, the model with the least validation RMSE was chosen
- Evaluation metric
  - Root mean square error skill score (RMSESS)  $\in [-\infty, 1]$ : 
$$\text{RMSESS} = 1 - \frac{\text{RMSE}_{\text{model}}}{\text{RMSE}_{\text{clim}}}$$
  - Compares the model forecasts with the 30-year climate normals ( $> 0$  means the model is better)

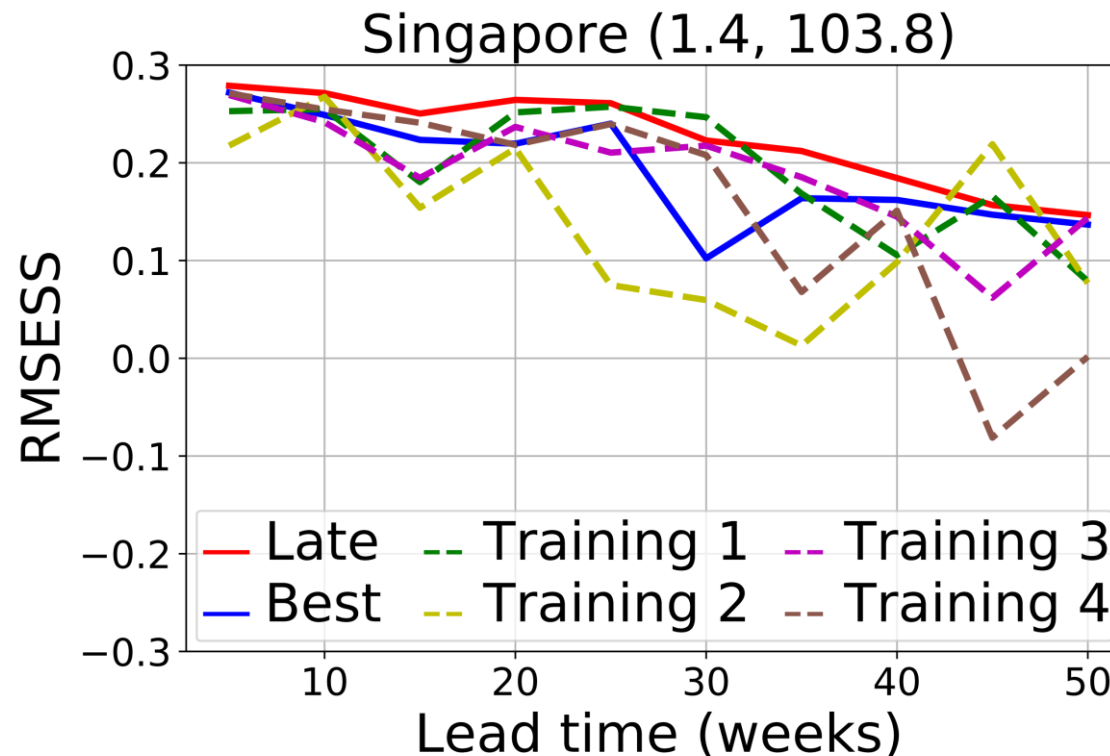
# Results

- Example of forecasts of a model on testing data with lead time = 5 weeks
  - Forecasts closely followed the ground truth
  - The model was able to predict the anomaly in 2016 (the hottest year on record)



# Results

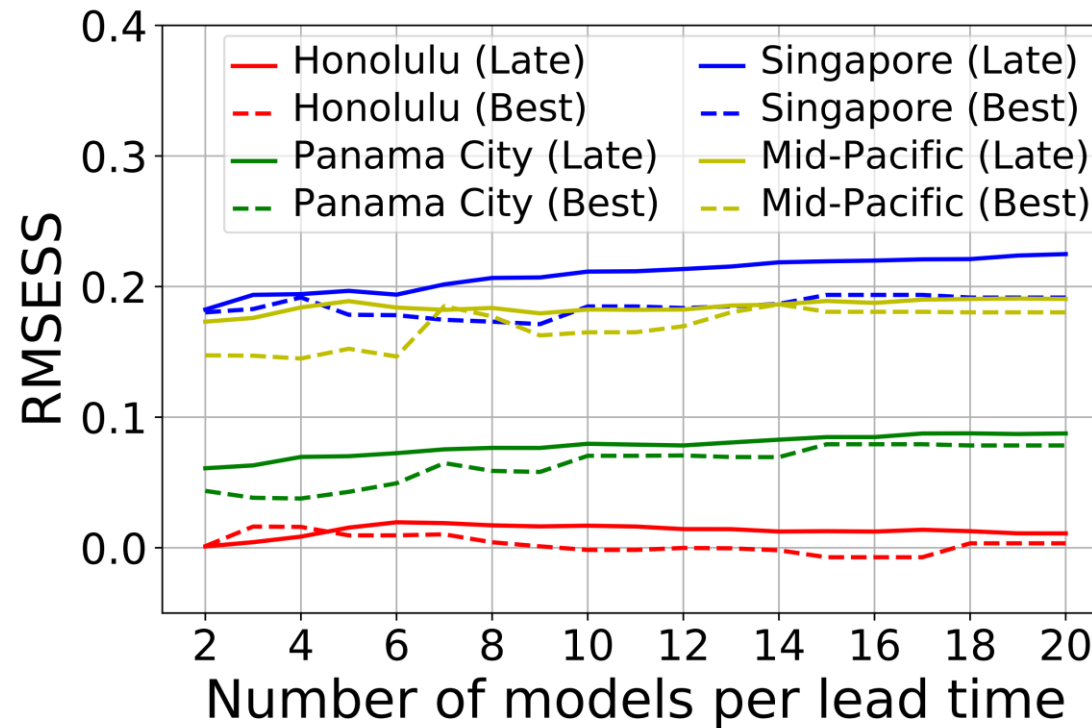
- Forecasts vs lead time
  - Most RMSESS > 0 → the models were better than climate normals
  - Models trained with same hyperparameters are different especially at large lead times
  - The late fusion framework outperformed the best model framework





# Results

- Performance with increasing number of models
  - The late fusion framework gradually improved, outperformed the best model



# Thanks!

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